



Traitement, Synthèse, Technologie et Applications

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RESTAURATION D'IMAGE TRANSFORMEE DE WALSH BIDIMENSIONNELLE IMAGE RESTAURATION BY THE USE OF 2-D DISCRETE WALSH TRANSFORMS

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RESUME

Un 2-D algorithme numérique de filtration, réalisé à l'aide de la 2-D transformation discrète de Walsh, est présenté dans le travail. L'algorithme résulte de l'application séquentielle d'une 1-D filtration aux lignes et colonnes de la matrice des données d'entrée. L'emploi de cet algorithme de filtration dans le processus de restauration des images est montré. Dans ce but une méthode de synthèse du filtre de restauration dans le domaine de Walsh est proposée. On suppose, que l'image est contaminée avec un bruit additif stationnaire, non-corrélé avec l'image originale. Pour ces suppositions les matrices de filtration, qui déterminent les propriétés du filtre numérique de restauration optimal (dans le domaine de Walsh) sont calculées. Le critère d'optimisation est exprimé par la valeur minimale de l'erreur carré moyen du processus de restauration. Un exemple de restauration de l'image, à l'aide de la 2-D transformation de Walsh, est donné.

SUMMARY

The 2-D digital filtering algorithm, which is realized by the use of 2-D discrete Walsh transform is described. The algorithm is a sequential application of 1-D filtering to the rows and columns of the input data matrix. The use of this filtering algorithm for an image restoration is presented. The method of synthesis of the Walsh domain restoration filter is proposed. It is assumed, that the image is blurred by additive stationary noise. The noise is uncorrelated with the original image. For these assumptions, the filter matrices characterizing the properties of the optimal digital Walsh domain restoration filter are calculated. The optimization criterion is the minimal value of the mean-square-error of the restoration process. An example of the image restoration by the use of the 2-D discrete Walsh transform is shown.

1. INTRODUCTION

One of the first steps in image processing particularly in image restoration, is the noise filtering to improve the signal to noise ratio. This can be accomplished by smoothing the discrete noise corrupted signal with an appropriate linear restoration filter. Usually we are interested in such filtering algorithms, which require as less

time as possible. The restoration filters are mainly based on the discrete Fourier series-transform technique [3]. The image restoration can be also achieved by filtering the noise by the use of the two-dimensional (2-D) discrete Walsh transform. The 2-D discrete Walsh transform can be computed much faster than the 2-D discrete Fourier transform. The restoration algorithm described in the paper [4] requires for its



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realization only $4N^2 \log_2 N$ real additions/subtractions and $2N^2$ real multiplications (N^2 denotes the number of samples). In this paper a restoration model in the Walsh domain for a smeared image with additive sta-

tionary noise is presented. Moreover the results of the digital image restoration are shown. An image field contained 32×32 points.

2. THE RESTORATION ALGORITHM

The block diagram of the image restoration algorithm in Walsh domain is shown in Fig.1.

The corresponding formula can be written as

$$\underline{U} = \underline{W}^{-1} \underline{G}_1^W \underline{W} \underline{V} \underline{W} \underline{G}_k^W \underline{W}^{-1} \quad (1)$$

where \underline{G}_k^W and \underline{G}_1^W are the filter matrices for the rows and columns of the input noisy image data matrix, \underline{V} is the $N \times N$ noisy image data matrix, \underline{U} is the $N \times N$ restored image matrix, \underline{W} denotes the $N \times N$ Walsh transform matrix with elements "+1" and "-1",

which are the values of the discrete Walsh functions in sequency ordering, \underline{W}^{-1} is the inverse matrix.

In this paper the filter matrices \underline{G}_k^W and \underline{G}_1^W , which express the properties of the Walsh domain restoration filter, are assumed to have a diagonal and constant form.

Therefore some image restoration error is to be expected. If the 2D sequency (Walsh) spectrum of the blurred image is known, the above mentioned error can be minimized [5].

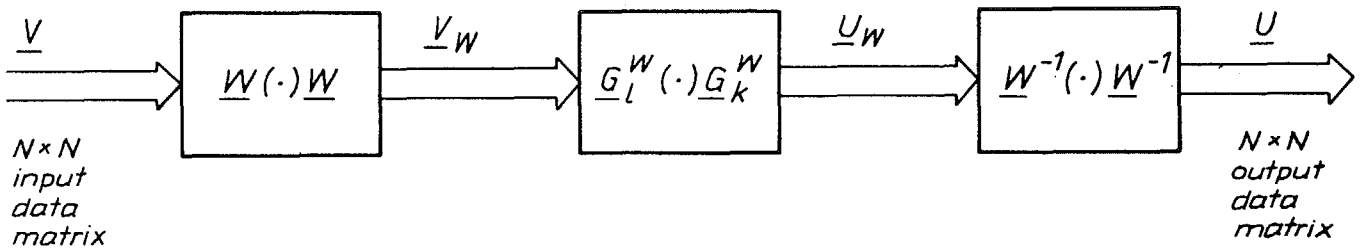


Fig.1. The block diagram of the Walsh domain restoration filter

3. THE RESTORATION FILTER

In the case of additive noise, the most accepted restoration technique is general Wiener filtering, which minimizes the mean square difference between the original and restored images. Our restoration model uses the 2D Walsh domain filter which is defined by the following equations.

$$\sum_{i=0}^{N-1} \left\{ G_1^W(j,j) E[V_w^2(i,j)] [G_k^W(i,i)]^2 + G_k^W(i,i) E[V_w(i,j) U_w(i,j)] \right\} = 0 \quad (2)$$

$$\sum_{j=0}^{N-1} \left\{ [G_1^W(j,j)]^2 E[V_w^2(i,j)] G_k^W(i,i) + G_1^W(j,j) E[V_w(i,j) U_w(i,j)] \right\} = 0$$

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where $G^W(j,j)$ and $G^W(i,i)$ are the unknown values of the $N \times N$ diagonal filter matrices G_1^W and G_k^W , respectively.

$E[V_w^2(i,j)]$ is the Walsh power density spectrum of the smeared image.

E denotes the expectation operator.

$E[V_w(i,j) U_w(i,j)]$ is the Walsh cross-power density spectrum.

The above system of equations can be solved by the use of the iteration method. Equations (2) result from the following condition

$$E \left\{ \frac{1}{N^2} \sum_{k=0}^{N-1} \sum_{l=0}^{N-1} [\hat{u}(k,l) - u(k,l)]^2 \right\} = \min \quad (3)$$

where $u(k,l)$ and $\hat{u}(k,l)$ are samples of the original and restored images, respectively. According to the Parseval's theorem, condition (3) can be expressed in the following form

$$E \left\{ \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} [\hat{U}_w(i,j) - U_w(i,j)]^2 \right\} = \min \quad (4)$$

where $U_w(i,j)$ and $\hat{U}_w(i,j)$ are the Walsh power spectra of the original and restored images.

Taking into account, that

$$\hat{U}_w(i,j) = G_1^W(j,j) V_w(i,j) G_k^W(i,i) \quad (5)$$

we have

$$E \left\{ \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} [G_1^W(j,j) V_w(i,j) G_k^W(i,i) - U_w(i,j)]^2 \right\} = \min \quad (6)$$

where $V_w(i,j)$ is the Walsh power spectrum of the smeared image with additive noise. Differentiating (6) with respect to $G_1^W(j,j)$ and $G_k^W(i,i)$ we have

$$\frac{\partial E \left\{ \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} [G_1^W(j,j) V_w(i,j) G_k^W(i,i) - U_w(i,j)]^2 \right\}}{\partial G_1^W(j,j)} =$$

$$= \sum_{i=0}^{N-1} 2 \left\{ G_1^W(j,j) E[V_w^2(i,j)] [G_k^W(i,i)]^2 - E[V_w(i,j) U_w(i,j)] G_k^W(i,i) \right\} \quad (7)$$

$$\frac{\partial E \left\{ \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} [G_1^W(j,j) V_w(i,j) G_k^W(i,i) - U_w(i,j)]^2 \right\}}{\partial G_k^W(i,i)} =$$

$$= \sum_{j=0}^{N-1} 2 \left\{ [G_1^W(j,j)]^2 E[V_w^2(i,j)] G_k^W(i,i) - G_1^W(j,j) E[V_w(i,j) U_w(i,j)] \right\} \quad (8)$$

For a minimum, these derivatives must be zero for each value of i and j ; hence the best choice of $G_1^W(j,j)$ and $G_k^W(i,i)$ is given by Eqs.(2).

4. RESULTS

Some computer-simulation results are shown in Figs. 2a, 2b, 2c.

An image of a numeral „5" (see [3]) was sampled to 32×32 points. Each point in the numeral was given a value 7, while each point outside the numeral was given a value 0. In the images shown in Figs. 2a, 2b, 2c, each point was quantized to 16 levels (0-15), the levels 10-15 being represented by the letters A-F. The original image, shown in Fig.2a was blurred by the additive noise (Fig.2b). The noise was independent of the original signal. Its standard deviation was equal 0,25 and the mean value 4. The Walsh filtering method was applied to this blurred image. The result after 10 iterations is shown in Fig.2c. It must be noted that even at this relatively low signal-to-noise ratio, the result of applying the Walsh filtering method is quite good.

