## Pseudo-marginal MCMC methods for inference in latent variable models

Arnaud Doucet<br>Department of Statistics, Oxford University Joint work with George Deligiannidis (Oxford) \& Mike Pitt (Kings)

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## Organization of the talk

- Latent variable models


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- Latent variable models
- The pseudo-marginal method


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- The correlated pseudo-marginal method
- Illustrations


## Latent Variable Models

- Assume

$$
X_{t} \stackrel{\text { i.i.d. }}{\sim} \mu_{\theta}(\cdot), \quad Y_{t} \mid\left(X_{t}=x\right) \sim g_{\theta}(\cdot \mid x) \text { for } t=1, \ldots, T
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where $\left(X_{t}\right)_{t \geq 1}$ are latent variables and $\left(Y_{t}\right)_{t \geq 1}$ correspond to observations.

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p_{\theta}\left(y_{1: T}\right)=\prod_{t=1}^{T} p_{\theta}\left(y_{t}\right), \text { where } p_{\theta}\left(y_{t}\right)=\int \mu_{\theta}\left(x_{t}\right) g_{\theta}\left(y_{t} \mid x_{t}\right) \mathrm{d} x_{t}
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- In many scenarios, $p_{\theta}\left(y_{1: T}\right)$ cannot be evaluated exactly.


## Example: Multivariate Probit model

- Multivariate latent Gaussian variables

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X_{t}=Z_{t} \beta+\varepsilon_{t}, \quad \varepsilon_{t} \stackrel{\text { i.i.d. }}{\sim} \mathcal{N}(0, R) .
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- Likelihood of $(\beta, R)$ is the product of $T$ integrals of $n$-dimensional truncated multivariate normals.


## State-Space Models

- Assume $\left\{X_{t}\right\}_{t \geq 1}$ is a latent Markov process, i.e. $X_{1} \sim \mu_{\theta}(\cdot)$ and

$$
X_{t+1}\left|\left(X_{t}=x\right) \sim f_{\theta}(\cdot \mid x), \quad Y_{t}\right|\left(X_{t}=x\right) \sim g_{\theta}(\cdot \mid x)
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- State-space models are ubiquitous in time series analysis but inference is difficult as $p_{\theta}\left(y_{1: T}\right)$ is intractable for non-linear/non-Gaussian models.


## Stochastic kinetic model - Lotka-Volterra

- Two species $X_{s}^{1}$ (prey) and $X_{s}^{2}$ (predator)

$$
\begin{aligned}
& \operatorname{Pr}\left(X_{s+d s}^{1}=x_{s}^{1}+1, X_{s+d s}^{2}=x_{s}^{2} \mid x_{s}^{1}, x_{s}^{2}\right)=\alpha x_{s}^{1} d s+o(d s), \\
& \operatorname{Pr}\left(X_{s+d s}^{1}=x_{s}^{1}-1, X_{s+d s}^{2}=x_{s}^{2}+1 \mid x_{s}^{1}, x_{s}^{2}\right)=\beta x_{s}^{1} x_{s}^{2} d s+o(d s), \\
& \operatorname{Pr}\left(X_{s+d s}^{1}=x_{t}^{1}, X_{s+d s}^{2}=x_{s}^{2}-1 \mid x_{s}^{1}, x_{s}^{2}\right)=\gamma x_{s}^{2} d s+o(d s),
\end{aligned}
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observed at discrete times

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Y_{t}=X_{\Delta t}^{1}+W_{t} \text { with } W_{t} \stackrel{\text { i.i.d. }}{\sim} \mathcal{N}\left(0, \sigma^{2}\right)
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- Kinetic rate constants $\theta=(\alpha, \beta, \gamma)$.


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- Signal Processing: target tracking.
- Systems biology: stochastic kinetic models.


## Bayesian Inference for Latent Variable Models

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- For non-trivial models, inference relies typically on MCMC.


## Standard MCMC Approaches

- Standard MCMC schemes target $p\left(\theta, x_{1: T} \mid y_{1: T}\right)$ where

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p\left(\theta, x_{1: T} \mid y_{1: T}\right) \propto p(\theta) p_{\theta}\left(x_{1: T}, y_{1: T}\right)
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using Gibbs type strategy; i.e. sample alternately $X_{1: T} \sim p_{\theta}\left(\cdot \mid y_{1: T}\right)$ and $\theta \sim p\left(\cdot \mid y_{1: T}, X_{1: T}\right)$.

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- Problem 1: it can be difficult to sample $p_{\theta}\left(x_{1: T} \mid y_{1: T}\right)$; e.g. state-space models.
- Problem 2: Even when it is implementable, Gibbs can converge very slowly.
- Pseudo-marginal methods mimick an algorithm targetting directly $p\left(\theta \mid y_{1: T}\right)$ instead of $p\left(\theta, x_{1: T} \mid y_{1: T}\right)$.


## Ideal Marginal Metropolis-Hastings algorithm

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set $\vartheta_{i}=\vartheta$, otherwise set $\vartheta_{i}=\vartheta_{i-1}$.


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& \min \{1, \underbrace{\frac{p_{\vartheta}\left(y_{1: T}\right)}{p_{\vartheta_{i-1}}\left(y_{1: T}\right)} \frac{p(\vartheta)}{p\left(\vartheta_{i-1}\right)} \frac{q\left(\vartheta_{i-1} \mid \vartheta\right)}{q\left(\vartheta \mid \vartheta_{i-1}\right)}}_{\text {exact MH ratio }} \times \underbrace{\frac{\hat{p}_{\vartheta}\left(y_{1: T}\right) / p_{\vartheta}\left(y_{1: T}\right)}{\hat{p}_{\vartheta_{i-1}}\left(y_{1: T}\right) / p_{\vartheta_{i-1}}\left(y_{1: T}\right)}}_{\text {noise }}\} \\
& \quad=\min \left\{1, \frac{\widehat{p}_{\vartheta}\left(y_{1: T}\right) p(\vartheta)}{\hat{p}_{\vartheta_{i-1}}\left(y_{1: T}\right) p\left(\vartheta_{i-1}\right)} \frac{q\left(\vartheta_{i-1} \mid \vartheta\right)}{q\left(\vartheta \mid \vartheta_{i-1}\right)}\right\} \\
& \text { set } \vartheta_{i}=\vartheta, \widehat{p}_{\vartheta_{i}}\left(y_{1: T}\right)=\widehat{p}_{\vartheta}\left(y_{1: T}\right) \text { otherwise set } \vartheta_{i}=\vartheta_{i-1}, \\
& \widehat{p}_{\vartheta_{i}}\left(y_{1: T}\right)=\widehat{p}_{\vartheta_{i-1}}\left(y_{1: T}\right) .
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## Key Result

- Proposition (Lin, Liu \& Sloan, 2000; Andrieu \& Roberts, 2009): If $\widehat{p}_{\vartheta}\left(y_{1: T}\right)$ is a non-negative unbiased estimator of $p_{\theta}\left(y_{1: T}\right)$ then the pseudo-marginal MH kernel admits $\pi(\theta)$ as invariant density.


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- Let $U$ be the r.v. such that $\hat{p}_{\theta}\left(y_{1: T}\right)=\widehat{p}_{\theta}\left(y_{1: T} ; U\right)$ and $\mathbb{E}\left[\widehat{p}_{\theta}\left(y_{1: T} ; U\right)\right]=p_{\theta}\left(y_{1: T}\right)$ when $U \sim m(\cdot)$.


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- Consider the auxiliary target density on $\Theta \times \mathcal{U}$

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\bar{\pi}(\theta, u)=\pi(\theta) \underbrace{\frac{\widehat{p}_{\theta}\left(y_{1: T} ; u\right)}{p_{\theta}\left(y_{1: T}\right)} m(u)}_{\int(.) \mathrm{d} u=1}
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- Pseudo-marginal MH is a standard MH with target $\bar{\pi}(\theta, u)$ and proposal $q(\vartheta \mid \theta) m(v)$ as

$$
\frac{\bar{\pi}(\vartheta, v)}{\bar{\pi}(\theta, u)} \frac{q(\theta \mid \vartheta) m(u)}{q(\vartheta \mid \theta) m(v)}=\frac{\widehat{p}_{\vartheta}\left(y_{1: T} ; v\right)}{\widehat{p}_{\theta}\left(y_{1: T} ; u\right)} \frac{p(\vartheta)}{p(\theta)} \frac{q(\theta \mid \vartheta)}{q(\vartheta \mid \theta)}
$$

## Importance Sampling Estimator

- For latent variable models, one has

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p_{\theta}\left(y_{t}\right)=\int \mu_{\theta}\left(x_{t}\right) g_{\theta}\left(y_{t} \mid x_{t}\right) \mathrm{d} x_{t}
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- An non-negative unbiased estimator is given by

$$
\widehat{p}_{\theta}\left(y_{1: T}\right)=\prod_{t=1}^{T} \widehat{p}_{\theta}\left(y_{t}\right)=\prod_{t=1}^{T}\left\{\frac{1}{N} \sum_{k=1}^{N} g_{\theta}\left(y_{t} \mid X_{t}^{k}\right)\right\}, \quad X_{t}^{k} \stackrel{\text { i.i.d. }}{\sim} \mu_{\theta},
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- Computational complexity is $O(N T)$.


## Particle Filter Estimator

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- For state-space models, previous approach provides an estimator whose relative variance scales typically exponentially with $T$.
- An alternative is to use particle filter where

$$
\begin{aligned}
\widehat{p}_{\theta}\left(y_{1: T}\right) & =\widehat{p}_{\theta}\left(y_{1}\right) \prod_{t=2}^{T} \widehat{p}_{\theta}\left(y_{t} \mid y_{1: t-1}\right) \\
& =\prod_{t=1}^{T}\left\{\frac{1}{N} \sum_{k=1}^{N} g_{\theta}\left(y_{t} \mid X_{n}^{k}\right)\right\}
\end{aligned}
$$

where

$$
m(u)=\prod_{k=1}^{N} \mu_{\theta}\left(x_{1}^{k}\right) \prod_{t=2}^{T}\left\{\prod_{k=1}^{N} w_{t}^{a_{t-1}^{k}} f\left(x_{t}^{k} \mid x_{t-1}^{a_{t-1}^{k}}\right)\right\}
$$

with $a_{t-1}^{k} \in\{1, \ldots, N\}, w_{t}^{j} \propto g_{\theta}\left(y_{t} \mid X_{t}^{j}\right), \sum_{j} w_{t}^{j}=1$.

## Particle Filter Estimator

- For state-space models, previous approach provides an estimator whose relative variance scales typically exponentially with $T$.
- An alternative is to use particle filter where

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\widehat{p}_{\theta}\left(y_{1: T}\right) & =\widehat{p}_{\theta}\left(y_{1}\right) \prod_{t=2}^{T} \hat{p}_{\theta}\left(y_{t} \mid y_{1: t-1}\right) \\
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- Computational complexity is $O(N T)$.
- The estimator $\hat{p}_{\theta}\left(y_{1: T}\right)$ of $p_{\theta}\left(y_{1: T}\right)$ is unbiased and its relative variance is bounded uniformly over $T$ if $N \propto T$ (Cerou; Del Moral \&


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- With probability

$$
\min \left\{1, \frac{\hat{p}_{\vartheta}\left(y_{1: T}\right) p(\vartheta)}{\hat{p}_{\vartheta_{i-1}}\left(y_{1: T}\right) p\left(\vartheta_{i-1}\right)} \frac{q\left(\vartheta_{i-1} \mid \vartheta\right)}{q\left(\vartheta \mid \vartheta_{i-1}\right)}\right\}
$$

set $\vartheta_{i}=\vartheta, \widehat{p}_{\vartheta_{i}}\left(y_{1: T}\right)=\widehat{p}_{\vartheta}\left(y_{1: T}\right)$ otherwise set $\vartheta_{i}=\vartheta_{i-1}$, $\widehat{p}_{\vartheta_{i}}\left(y_{1: T}\right)=\widehat{p}_{\vartheta_{i-1}}\left(y_{1: T}\right)$.

## Empirical performance: Stochastic kinetic model

- Two species $X_{s}^{1}$ (prey) and $X_{s}^{2}$ (predator)

$$
\begin{aligned}
& \operatorname{Pr}\left(X_{s+d s}^{1}=x_{s}^{1}+1, X_{s+d s}^{2}=x_{s}^{2} \mid x_{s}^{1}, x_{s}^{2}\right)=\alpha x_{s}^{1} d s+o(d s), \\
& \operatorname{Pr}\left(X_{s+d s}^{1}=x_{s}^{1}-1, X_{s+d s}^{2}=x_{s}^{2}+1 \mid x_{s}^{1}, x_{s}^{2}\right)=\beta x_{s}^{1} x_{s}^{2} d s+o(d s), \\
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\end{aligned}
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observed at discrete times

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- We are interested in the kinetic rate constants $\theta=(\alpha, \beta, \gamma)$ a priori distributed as (Boys et al., 2008; Kunsch, 2011)

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\alpha \sim \mathcal{G}(1,10), \quad \beta \sim \mathcal{G}(1,0.25), \quad \gamma \sim \mathcal{G}(1,7.5)
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- Pseudo-marginal MH with RW proposal, likelihood is approximated using particle filter.


## Empirical performance: Stochastic kinetic model









Simulated data
Estimated posteriors


## Empirical performance: Stochastic kinetic model




Autocorrelation of $\alpha$ (left) and $\beta$ (right) for the PM sampler for various $N$.

## Empirical performance: Stochastic volatility model

- Huang \& Tauchen, J. Financial Econometrics (2005):

$$
\begin{aligned}
\mathrm{d} v_{1}(s) & =-k_{1}\left\{v_{1}(s)-\mu_{1}\right\} \mathrm{d} s+\sigma_{1} \mathrm{~d} W_{1}(s), \\
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\mathrm{d} \log P(s) & =\mu_{y} \mathrm{~d} s+\mathrm{s}-\exp \left[\left\{v_{1}(s)+\beta_{2} v_{2}(s)\right\} / 2\right] \mathrm{d} B(s),
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- Bayesian Inference on $\theta=\left(k_{1}, \mu_{1}, \sigma_{1}, k_{2}, \beta_{12}, \beta_{2}, \mu_{y}, \phi_{1}, \phi_{2}\right)$.
- Performance of the pseudo-marginal for RW proposal w.r.t $\sigma$, standard deviation of $\log \widehat{p}_{\theta}(y)$ at posterior mean $\bar{\theta}$.


## Integrated Autocorrelation Time of Pseudo-Marginal MH



Figure: Average over the 9 parameter components of the log-integrated autocorrelation time of pseudo-marginal chain as a function of $\sigma$ for $T=300$.

## How precise should the log-likelihood estimator be?

- Aim: Minimize the computational time

$$
C T_{h}^{Q}=I F_{h}^{Q} / \sigma^{2}
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as $\sigma^{2} \propto 1 / N$ and computational efforts proportional to $N$, where $I F_{h}^{Q}=$ Integrated Autocorrelation Time of PM average

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- Call the IACT the inefficiency

$$
I F_{h}^{Q}=1+2 \sum_{\tau=1}^{\infty} \operatorname{corr}_{\bar{\pi}, Q}\left\{h\left(\theta_{0}\right), h\left(\theta_{\tau}\right)\right\}
$$

where $Q$ is the pseudo-marginal kernel given for $(\theta, z) \neq(\vartheta, w)$ by
$Q\{(\theta, z),(\mathrm{d} \vartheta, \mathrm{d} w)\}=q(\vartheta \mid \theta) g_{\vartheta}(w) \min \left\{1, \frac{\pi(\vartheta)}{\pi(\theta)} \exp (w-z)\right\} \mathrm{d} \vartheta \mathrm{d} w$, where

$$
\begin{aligned}
z & =\log \left\{\widehat{p}_{\theta}\left(y_{1: T}\right) / p_{\theta}\left(y_{1: T}\right)\right\} \\
w & =\log \left\{\widehat{p}_{\vartheta}\left(y_{1: T}\right) / p_{\vartheta}\left(y_{1}: T\right)\right\}
\end{aligned}
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## Computational time for the SV model



Figure: Computational time as a function of $\sigma$

## Analysis in the large data regime

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- Assumption 1 - Asymptotic Normality: We have

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- Assumption 2 - CLT: For any $\theta$ in a neighbourhood of $\bar{\theta}$,

$$
\left.\log \frac{\widehat{p}_{\theta}\left(Y_{1: T}\right)}{p_{\theta}\left(Y_{1: T}\right)} \right\rvert\, \mathcal{Y}^{T} \Rightarrow \mathcal{N}\left(-\sigma^{2}(\theta) / 2, \sigma^{2}(\theta)\right)
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in probability and $\sigma^{2}(\cdot)$ continuous at $\bar{\theta}$.

- Assumption 3 - Proposal: $\vartheta=\theta+\varepsilon / \sqrt{T}$ where $\varepsilon \sim v(\cdot)$ with $v(\varepsilon)=v(-\varepsilon)$.


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- Assumption 1 holds if for example Bernstein-von Mises holds (in correctly specified/misspecified scenarios).
- Assumption 2 has been shown to hold under regularity assumptions if $N \propto T$ (Berard et al, 2014, Deligiannidis et al, 2015).
- Assumption 3 can be easily enforced.


## Weak convergence

- Let $\left\{\vartheta_{i}^{T}, Z_{i}^{T}:=\log \widehat{p}_{\vartheta_{i}^{T}}\left(Y_{1: T}\right) / p_{\vartheta_{i}^{T}}\left(Y_{1: T}\right)\right\}_{i \geq 0}$ the stationary PM Markov chain of invariant density $p\left(\theta \mid Y_{1: T}\right) \exp (z) g_{\theta}^{T}(z)$.


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- Proposition (Schmon et al, 2016): The F.D.D. of the rescaled sequence $\left\{\tilde{\vartheta}_{i}^{T}=\sqrt{T}\left(\vartheta_{i}^{T}-\widehat{\theta}_{T}\right), Z_{i}^{T}\right\}_{i \geq 0}$ converge weakly as $T \rightarrow \infty$ to those of a stationary Markov chain of invariant density $\phi(\widetilde{\theta} ; 0, \Sigma) \phi\left(z ;-\sigma^{2}(\bar{\theta}) / 2, \sigma^{2}(\bar{\theta})\right)$ and kernel given by

$$
\begin{aligned}
\widetilde{Q}\{(\widetilde{\theta}, z),(\mathrm{d} \widetilde{\vartheta}, \mathrm{~d} w)\}= & v(\widetilde{\vartheta}-\widetilde{\theta}) \phi\left(w ;-\sigma^{2}(\bar{\theta}) / 2, \sigma^{2}(\bar{\theta})\right) \\
& \times \min \left\{1, \frac{\phi(\widetilde{\vartheta} ; 0, \Sigma)}{\phi(\widetilde{\theta} ; 0, \Sigma)} \exp (w-z)\right\} \mathrm{d} \widetilde{\vartheta} \mathrm{~d} w
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for $(\widetilde{\theta}, z) \neq(\widetilde{\vartheta}, w)$.

## Weak convergence

- These results suggests that a simplified analysis of the PM chain can be performed by looking at

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- It would be more satisfactory to show that

$$
\left|I F_{h}^{Q}-I F_{h}^{\widehat{Q}}\right| \rightarrow 0
$$

as $T \rightarrow \infty$. The analysis relies on (Andrieu \& Vihola, 2015) and is much more involved.

## Empirical vs Assumed Distributions for SV model











Figure: Empirical distributions (dashed) vs assumed Gaussians (solid) of $Z$ at $\bar{\theta}$ (left) and marginalized over samples from $\pi(\theta)$ (center) and $\int \pi(d \vartheta) q(\theta \mid \vartheta)$ (right) for $T=40, T=300$ and $T=2700$.

## Available Results

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(2) When $\pi(\theta)=\prod_{i=1}^{d} f\left(\theta_{i}\right)$ and $q(\vartheta \mid \theta)$ is an isotropic Gaussian random walk then, as $d \rightarrow \infty$, diffusion limit suggests $\sigma_{\text {opt }}=1.81$ (Sherlock et al., 2015).


## Sketch of the Analysis

- For general proposals and targets, direct minimization of $C T_{h}^{\widehat{Q}}(\sigma)=I F_{h}^{\widehat{Q}}(\sigma) / \sigma^{2}$ impossible so minimize an upper bound over it.


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- Peskun's theorem (1973) guarantees that $I F_{h}^{\widehat{Q}}(\sigma) \leq I F_{h}^{Q^{*}}(\sigma)$ so that $C T_{h}^{\widehat{Q}}(\sigma) \leq C T_{h}^{Q^{*}}(\sigma)$.


## Main Theoretical Result

- Proposition: If $I F_{h}^{Q^{*}}(\sigma)<\infty$ then $I F_{h}^{\widehat{Q}}(\sigma) \leq I F_{h}^{Q^{*}}(\sigma)$ and

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& \times \sum_{n=0}^{\infty} \phi_{n}\left(h / \varrho_{\mathrm{EX}}, \widetilde{Q}^{\mathrm{EX}}\right) \phi_{n}\left(1 / \varrho_{\mathrm{Z}}, \widetilde{Q}_{\sigma}^{\mathrm{Z}}\right) \\
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- This identity allows us to "decouple" the influence of the parameter and noise components on $I F_{h}^{Q^{*}}(\sigma)$.


## Simpler Bounds on the Relative Inefficiency

- If $I F_{h / \varrho_{\mathrm{EX}}}^{\widetilde{Q}^{\mathrm{EX}}} \geq 1$, e.g. $\widetilde{Q}^{\mathrm{EX}}$ is a positive kernel, then

$$
\frac{I F_{h}^{\widehat{Q}}(\sigma)}{I F_{h}^{E X}} \leq \frac{I F_{h}^{Q^{*}}(\sigma)}{I F_{h}^{E X}} \leq \frac{1}{2}\left(1+1 / I F_{h}^{\mathrm{EX}}\right) \pi_{\mathrm{Z}}^{\sigma}\left(1 / \varrho_{\mathrm{Z}}^{\sigma}\right)-\frac{1}{I F_{h}^{\mathrm{EX}}}
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- Results used to minimize w.r.t $\sigma$ upper bounds on $C T_{h}^{\widehat{Q}}(\sigma)=I F_{h}^{\widehat{Q}}(\sigma) / \sigma^{2}$.


## Bounds on Relative Computational Time




Left: upper bound on $C T_{h}^{Q^{*}}(\sigma) / I F_{h}^{E X}$ as a function of $\sigma$ for $I F_{h}^{E X}=1$ (square), 4 (crosses), 20 (circles), 80 (triangles). Right: upper bounds on $C T_{h}^{Q^{*}}(\sigma) / I F_{h}^{\mathrm{EX}}$ as a function of $\sigma$ for $I F_{J, h / / \varrho_{\mathrm{EX}}}^{\mathrm{EX}}=1$ for $I F_{J, h / / \varrho_{\mathrm{EX}}}^{\mathrm{EX}}=1,4,20,80$ and lower bound (solid line).

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(3) If $\sigma_{\text {opt }}=1.0$ or $\sigma_{\text {opt }}=1.7$ and you pick $\sigma=1.2-1.3$, computing time increases by $\approx 15 \%$.


## Example: Noisy Autoregressive Example

- Consider

$$
\begin{aligned}
& X_{t}=\mu(1-\phi)+\phi X_{t}+V_{t}, \quad V_{t} \stackrel{\text { i.i.d. }}{\sim} \mathcal{N}\left(0, \sigma_{\eta}^{2}\right), \\
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- Likelihood can be computed exactly using Kalman.
- Autoregressive Metropolis proposal of coefficient $\rho$ for $\vartheta$ based on multivariate t-distribution.
- $N$ is selected so as to obtain $\sigma(\bar{\theta}) \approx$ constant where $\bar{\theta}$ posterior mean.


## Relative Inefficiency and Computing Time



Figure: From left to right: $R C T_{h}^{Q}$ vs $N, R C T_{h}^{Q}$ vs $\sigma(\bar{\theta}), R I F_{h}^{Q}$ against $N$ and $R I F_{h}^{Q}$ against $\sigma(\bar{\theta})$ for various values of $\rho$ and different parameters.

## Discussion

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- Pseudo-marginal MH scales in $\mathcal{O}\left(T^{2}\right)$ as we require $N \propto T$, while simulated likelihood scales in $\mathcal{O}\left(T^{3 / 2}\right)$, i.e. $N \propto \sqrt{T}$.


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- However, pseudo-marginal MH much more generally applicable than simulated likelihood.


## The Correlated Pseudo-Marginal Algorithm

- Reparameterize the likelihood estimator $\hat{p}_{\theta}\left(y_{1: T}\right)$ as a function of normal variates $U \sim \mathcal{N}(0, I)$

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- In practice, $\rho$ will be select close to 1 .


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$$
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$$

set $\vartheta_{i}=\vartheta, U_{i}=V$, otherwise set $\vartheta_{i}=\vartheta_{i-1}, U_{i}=U_{i-1}$.

## Analysis in the large data regime - i.i.d. case

Proposition. Let $N=N(T) \rightarrow \infty$ as $T \rightarrow \infty$ with $N=o(T)$. When $U \sim \bar{\pi}(\cdot \mid \theta)$ and $V=\rho_{T} U+\sqrt{1-\rho_{T}^{2}} \varepsilon$ with $\rho_{T}=\exp \left(-\psi \frac{N}{T}\right)$ then as $T \rightarrow \infty$

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- This CLT is conditional on the observation sequence and the current auxiliary variables.
- Asymptotically the distribution of the log-ratio decouples from the current location of the Markov chain.
- The asymptotic variance is $O(1)$ even for $N \sim \log (T)$.


## Analysis in the large data regime

- Assumption 1 - Asymptotic Normality: We have

$$
\int\left|p\left(\theta \mid Y_{1: T}\right)-\phi\left(\theta ; \widehat{\theta}^{T}, \Sigma / T\right)\right| \mathrm{d} \theta \xrightarrow{P} 0
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- Assumption 3 - For any $\theta$ in a neighbourhood of $\bar{\theta}$, the conditional CLT holds and $\kappa^{2}(\cdot)$ is continuous at $\bar{\theta}$.


## Weak convergence

- Let $\left\{\vartheta_{i}^{T}\right\}_{i \geq 0}$ the stationary non-Markovian sequence of the correlated PM of invariant density $p\left(\theta \mid Y_{1: T}\right)$.


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- These results suggests that a simplified analysis of the CPM chain can be performed by looking at

$$
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where $\mathbb{E}\left(\theta_{0} \mid U_{0}\right) \approx \widehat{\theta}^{T}+\Sigma / T \nabla_{\theta} \log \widehat{p}_{\theta}\left(y_{1: T} ; U\right) /\left.p_{\theta}\left(y_{1: T}\right)\right|_{\widehat{\theta}^{T}}$. and $I F_{h}^{Q} \rightarrow \infty$ if $N / \sqrt{T} \rightarrow 0$.

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\operatorname{Cov}\left(\theta_{0}, \theta_{\tau}\right) \approx \underbrace{\mathbb{E}\left(\mathbb{C}\left(\theta_{0}, \theta_{\tau} \mid U_{0}, U_{\tau}\right)\right)}_{\text {fast }}+\underbrace{\mathbb{C}\left(\mathbb{E}\left(\theta_{0} \mid U_{0}\right), \mathbb{E}\left(\theta_{\tau} \mid U_{\tau}\right)\right)}_{\text {slow }}
$$

where $\mathbb{E}\left(\theta_{0} \mid U_{0}\right) \approx \widehat{\theta}^{T}+\Sigma / T \nabla_{\theta} \log \widehat{p}_{\theta}\left(y_{1: T} ; U\right) /\left.p_{\theta}\left(y_{1: T}\right)\right|_{\widehat{\theta}^{T}}$. and $I F_{h}^{Q} \rightarrow \infty$ if $N / \sqrt{T} \rightarrow 0$.

- To ensure $I F_{h}^{Q}$, we need at least $N \propto \sqrt{T}$ and we conjecture it is sufficient.


## Example: Gaussian Latent Variable Model

- Consider the toy model

$$
X_{t} \stackrel{\text { i.i.d. }}{\sim} \mathcal{N}(\theta, 1), \quad Y_{t} \mid X_{t} \sim \mathcal{N}\left(X_{t}, \sigma^{2}\right)
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- Integrated Autocorrelation Time is referred to as the Inefficiency IF.


## Example: Gaussian Latent Variable Model

| $\mathrm{MH}(T=8192)$ |  | $\mathrm{IF}(\theta)$ |  |
| :--- | :--- | :--- | ---: |
| $\mathrm{PM}(\rho=0.0)$ |  | 15.6 |  |
| $N$ |  | $\mathrm{RIF}(\theta)$ | $\mathrm{RCT}(\theta)$ |
| 5000 |  | 2.2 | 11210 |
| $\mathrm{CPM}(\rho=0.9963)$ |  |  |  |
| $N$ | $\kappa$ | $\mathrm{RIF}(\theta)$ | $\mathrm{RCT}(\theta)$ |
| 9 | 3.1 | 14.0 | 126.2 |
| 12 | 2.7 | 8.3 | 99.7 |
| 20 | 2.2 | 4.7 | 93.3 |
| 25 | 2.0 | 2.8 | 69.3 |
| 35 | 1.7 | 1.7 | 61.1 |
| 56 | 1.3 | 1.6 | 87.0 |
| 80 | 1.1 | 1.1 | 89.0 |
| 120 | 0.9 | 0.9 | 113.5 |

Here RIF $=\mathrm{IF} / \mathrm{IF}_{M H}$ and $\mathrm{RCT}=N \times$ RIF.

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## Discussion

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- Analysis suggests that complexity is $O(T \sqrt{T})$ vs $O\left(T^{2}\right)$.
- In state-space models, implementation relies on non-standard particle filter scheme (Hilbert sorting): our analysis does not hold experimentally for state dimension $>1$ and theoretically and but still substantial gains.
- Novel pseudo-marginal scheme using Conditional Sequential Monte Carlo (Andrieu, A.D., Yildirim, 2016) appears to suggest $O(T)$ is feasible.


## Experimental results using conditional SMC

|  | Novel c-SMC PM |  | Standard PM |  |
| :--- | :--- | :--- | :--- | :--- |
|  | $\sigma_{v}^{2}$ | $\sigma_{w}^{2}$ | $\sigma_{v}^{2}$ | $\sigma_{w}^{2}$ |
| $T=1000$ | 17.7 | 23.5 | 71.2 | 59.2 |
| $T=2000$ | 17.5 | 23.7 | 759.0 | 757.9 |
| $T=5000$ | 17.6 | 23.7 | 5808.6 | 5663.5 |
| $T=10000$ | 17.6 | 23.6 | 7368.1 | 7176.9 |

Estimated IACT on a nonlinear state-space model for $N=200$ for novel c-SMC PM algorithm and $N=2000$ for standard PM algorithm

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