Pseudo-marginal MCMC methods for inference in latent variable models

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07/07/2016



• Latent variable models



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- Latent variable models
- The pseudo-marginal method

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- Optimal tuning



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- Illustrations

Assume

$$X_{t} \stackrel{\text{i.i.d.}}{\sim} \mu_{\theta}\left(\cdot\right)$$
, $Y_{t} | \left(X_{t} = x\right) \sim g_{\theta}\left(\cdot | x\right)$ for $t = 1, ..., T$

where $(X_t)_{t\geq 1}$ are latent variables and $(Y_t)_{t\geq 1}$ correspond to observations.

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• The likelihood of $Y_{1:\mathcal{T}} = y_{1:\mathcal{T}}$ for parameter $heta \in \mathbb{R}^d$ is

$$p_{\theta}\left(y_{1:T}\right) = \prod_{t=1}^{T} p_{\theta}\left(y_{t}\right), \text{ where } p_{\theta}\left(y_{t}\right) = \int \mu_{\theta}\left(x_{t}\right) g_{\theta}\left(y_{t} \middle| x_{t}\right) \mathrm{d}x_{t}.$$

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ight) \mathrm{d}x_{t}$.

• In many scenarios, $p_{ heta}\left(y_{1:T}
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• Multivariate latent Gaussian variables

$$X_t = Z_t \beta + \varepsilon_t, \quad \varepsilon_t \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, R).$$

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• Likelihood of (β, R) is the product of T integrals of *n*-dimensional truncated multivariate normals.

State-Space Models

• Assume $\{X_t\}_{t\geq 1}$ is a latent Markov process, i.e. $X_1\sim \mu_ heta(\cdot)$ and

$$X_{t+1}|(X_t = x) \sim f_{\theta}(\cdot|x), \quad Y_t|(X_t = x) \sim g_{\theta}(\cdot|x).$$

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• The likelihood of observations $Y_{1:T} = y_{1:T}$ is

$$p_{\theta}(y_{1:T}) = \int p_{\theta}(x_{1:T}, y_{1:T}) \mathrm{d}x_{1:T}$$

where

$$p_{\theta}(x_{1:T}, y_{1:T}) = \mu_{\theta}(x_1)g_{\theta}(y_1|x_1)\prod_{t=2}^{T} f_{\theta}(x_t|x_{t-1})g_{\theta}(y_t|x_t).$$

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 State-space models are ubiquitous in time series analysis but inference is difficult as p_θ(y_{1:T}) is intractable for non-linear/non-Gaussian models.

• Two species X_s^1 (prey) and X_s^2 (predator)

$$\begin{array}{l} \Pr\left(X_{s+ds}^{1}\!=\!\!x_{s}^{1}\!\!+\!\!1,X_{s+ds}^{2}\!=\!\!x_{s}^{2}\!\left|\,x_{s}^{1},x_{s}^{2}\right.\right) = \alpha\,x_{s}^{1}ds + o\left(ds\right), \\ \Pr\left(X_{s+ds}^{1}\!=\!\!x_{s}^{1}\!\!-\!\!1,X_{s+ds}^{2}\!=\!\!x_{s}^{2}\!\!+\!\!1\!\left|\,x_{s}^{1},x_{s}^{2}\right.\right) = \beta\,x_{s}^{1}\,x_{s}^{2}ds + o\left(ds\right), \\ \Pr\left(X_{s+ds}^{1}\!=\!\!x_{t}^{1},X_{s+ds}^{2}\!=\!\!x_{s}^{2}\!\!-\!\!1\!\left|\,x_{s}^{1},x_{s}^{2}\right.\right) = \gamma\,x_{s}^{2}ds + o\left(ds\right), \end{array}$$

observed at discrete times

$$Y_t = X^1_{\Delta t} + W_t$$
 with $W_t \stackrel{ ext{i.i.d.}}{\sim} \mathcal{N}\left(0, \sigma^2
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• Kinetic rate constants $\theta = (\alpha, \beta, \gamma)$.

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- Systems biology: stochastic kinetic models.

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- Bayesian inference relies on the posterior

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• For non-trivial models, inference relies typically on MCMC.

Standard MCMC Approaches

• Standard MCMC schemes target $p(\theta, x_{1:T} | y_{1:T})$ where

$$p(\theta, x_{1:T} | y_{1:T}) \propto p(\theta) p_{\theta}(x_{1:T}, y_{1:T})$$

using Gibbs type strategy; i.e. sample alternately $X_{1:T} \sim p_{\theta}(\cdot | y_{1:T})$ and $\theta \sim p(\cdot | y_{1:T}, X_{1:T})$. • Standard MCMC schemes target $p(\theta, x_{1:T} | y_{1:T})$ where

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- Problem 1: it can be difficult to sample p_θ (x_{1:T} | y_{1:T}); e.g. state-space models.
- **Problem** 2: Even when it is implementable, Gibbs can converge very slowly.
- Pseudo-marginal methods mimick an algorithm targetting directly $p(\theta|y_{1:T})$ instead of $p(\theta, x_{1:T}|y_{1:T})$.

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Ideal Marginal Metropolis-Hastings algorithm

• Metropolis–Hastings (MH) algorithm simulates an ergodic Markov chain $\{\vartheta_i\}_{i\geq 1}$ of limiting distribution $\pi(\theta)$.

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$$\min\left\{1, \frac{\pi\left(\vartheta\right)}{\pi\left(\vartheta_{i-1}\right)} \frac{q\left(\vartheta_{i-1} \middle| \vartheta\right)}{q\left(\vartheta \middle| \vartheta_{i-1}\right)}\right\} = \min\left\{1, \frac{p_{\vartheta}\left(y_{1:T}\right) p\left(\vartheta\right)}{p_{\vartheta_{i-1}}\left(y_{1:T}\right) p\left(\vartheta_{i-1}\right)} \frac{q\left(\vartheta_{i-1} \middle| \vartheta\right)}{q\left(\vartheta \middle| \vartheta_{i-1}\right)}\right\},$$

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• "Idea": Replace $p_{\vartheta}(y_{1:T})$ by an estimate $\hat{p}_{\vartheta}(y_{1:T})$ in MH.

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set $\vartheta_{i} = \vartheta, \, \hat{p}_{\vartheta_{i}}\left(y_{1:T}\right) = \hat{p}_{\vartheta}\left(y_{1:T}\right) \text{ otherwise set } \vartheta_{i} = \vartheta_{i-1},$
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• **Proposition** (Lin, Liu & Sloan, 2000; Andrieu & Roberts, 2009): If $\hat{p}_{\theta}(y_{1:T})$ is a non-negative unbiased estimator of $p_{\theta}(y_{1:T})$ then the pseudo-marginal MH kernel admits $\pi(\theta)$ as invariant density.

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- Let U be the r.v. such that $\widehat{p}_{\theta}(y_{1:T}) = \widehat{p}_{\theta}(y_{1:T}; U)$ and $\mathbb{E}\left[\widehat{p}_{\theta}(y_{1:T}; U)\right] = p_{\theta}(y_{1:T})$ when $U \sim m(\cdot)$.

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- \bullet Consider the auxiliary target density on $\Theta\times \mathcal{U}$

$$\overline{\pi}(\theta, u) = \pi\left(\theta\right) \underbrace{\frac{\widehat{p}_{\theta}\left(y_{1:T}; u\right)}{p_{\theta}\left(y_{1:T}\right)}m\left(u\right)}_{\int (.) \mathrm{d}u = 1}$$

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$$\overline{\pi}(\theta, u) = \pi\left(\theta\right) \underbrace{\frac{\widehat{p}_{\theta}\left(y_{1:T}; u\right)}{p_{\theta}\left(y_{1:T}\right)}m\left(u\right)}_{\int (.) \mathrm{d}u = 1}$$

• Pseudo-marginal MH is a standard MH with target $\overline{\pi}(\theta, u)$ and proposal $q(\vartheta|\theta) m(v)$ as

$$\frac{\overline{\pi}(\vartheta, v)}{\overline{\pi}(\theta, u)} \frac{q\left(\theta \mid \vartheta\right) m(u)}{q\left(\vartheta \mid \theta\right) m(v)} = \frac{\widehat{p}_{\vartheta}\left(y_{1:T}; v\right)}{\widehat{p}_{\theta}\left(y_{1:T}; u\right)} \frac{p\left(\vartheta\right)}{p\left(\theta\right)} \frac{q\left(\theta \mid \vartheta\right)}{q\left(\vartheta \mid \theta\right)}$$

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Importance Sampling Estimator

• For latent variable models, one has

$$p_{\theta}(y_t) = \int \mu_{\theta}(x_t) g_{\theta}(y_t | x_t) dx_t.$$

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• An non-negative unbiased estimator is given by

$$\widehat{p}_{\theta}(y_{1:T}) = \prod_{t=1}^{T} \widehat{p}_{\theta}(y_t) = \prod_{t=1}^{T} \left\{ \frac{1}{N} \sum_{k=1}^{N} g_{\theta}\left(y_t | X_t^k\right) \right\}, \ X_t^k \stackrel{\text{i.i.d.}}{\sim} \mu_{\theta},$$

i.e.

$$m(u) = \prod_{t=1}^{T} \prod_{k=1}^{N} \mu_{\theta}\left(x_{t}^{k}\right).$$

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$$= \prod_{t=1}^{T} \left\{ \frac{1}{N} \sum_{k=1}^{N} g_{\theta}\left(y_{t} | X_{n}^{k}\right) \right\}$$

where

$$\begin{split} m\left(u\right) &= \prod_{k=1}^{N} \mu_{\theta}\left(x_{1}^{k}\right) \prod_{t=2}^{T} \{\prod_{k=1}^{N} w_{t}^{a_{t-1}^{k}} f\left(x_{t}^{k} \middle| x_{t-1}^{a_{t-1}^{k}}\right)\}\\ \text{with } a_{t-1}^{k} &\in \{1, ..., N\} \text{, } w_{t}^{j} \propto g_{\theta}\left(y_{t} \middle| X_{t}^{j}\right) \text{, } \sum_{j} w_{t}^{j} = 1. \end{split}$$

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- Computational complexity is O(NT).
- The estimator $\hat{p}_{\theta}(y_{1:T})$ of $p_{\theta}(y_{1:T})$ is unbiased and its relative variance is bounded uniformly over T if $N \propto T$ (Cerou, Del Moral & (07/07/2016)

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With probability

$$\min\{1, \frac{\widehat{p}_{\vartheta}(y_{1:T}) p(\vartheta)}{\widehat{p}_{\vartheta_{i-1}}(y_{1:T}) p(\vartheta_{i-1})} \frac{q(\vartheta_{i-1}|\vartheta)}{q(\vartheta|\vartheta_{i-1})}\}$$

set $\vartheta_i = \vartheta$, $\widehat{p}_{\vartheta_i}(y_{1:T}) = \widehat{p}_{\vartheta}(y_{1:T})$ otherwise set $\vartheta_i = \vartheta_{i-1}$, $\widehat{p}_{\vartheta_i}(y_{1:T}) = \widehat{p}_{\vartheta_{i-1}}(y_{1:T})$.

• Two species
$$X_s^1$$
 (prey) and X_s^2 (predator)

$$\begin{array}{l} \Pr\left(X_{s+ds}^{1} \!=\! x_{s}^{1} \!+\! 1, X_{s+ds}^{2} \!=\! x_{s}^{2} \left| x_{s}^{1}, x_{s}^{2} \right) = \alpha \, x_{s}^{1} ds + o \left(ds \right), \\ \Pr\left(X_{s+ds}^{1} \!=\! x_{s}^{1} \!-\! 1, X_{s+ds}^{2} \!=\! x_{s}^{2} \!+\! 1 \left| x_{s}^{1}, x_{s}^{2} \right) = \beta \, x_{s}^{1} \, x_{s}^{2} ds + o \left(ds \right), \\ \Pr\left(X_{s+ds}^{1} \!=\! x_{t}^{1}, X_{s+ds}^{2} \!=\! x_{s}^{2} \!-\! 1 \right| x_{s}^{1}, x_{s}^{2} \right) = \gamma \, x_{s}^{2} ds + o \left(ds \right), \end{array}$$

observed at discrete times

$$Y_t = X_{\Delta t}^1 + W_t$$
 with $W_t \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma^2)$.

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We are interested in the kinetic rate constants θ = (α, β, γ) a priori distributed as (Boys et al., 2008; Kunsch, 2011)

$$\alpha \sim \mathcal{G}(1, 10), \quad \beta \sim \mathcal{G}(1, 0.25), \quad \gamma \sim \mathcal{G}(1, 7.5).$$

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(07/07/2016)



Autocorrelation of α (left) and β (right) for the PM sampler for various N.

(07/07/2016)

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• Huang & Tauchen, J. Financial Econometrics (2005):

$$\begin{aligned} dv_{1}(s) &= -k_{1} \{ v_{1}(s) - \mu_{1} \} ds + \sigma_{1} dW_{1}(s) , \\ dv_{2}(s) &= -k_{2} v_{2}(s) ds + \{ 1 + \beta_{12} v_{2}(s) \} dW_{2}(s) , \\ d\log P(s) &= \mu_{y} ds + \text{s-exp} \left[\{ v_{1}(s) + \beta_{2} v_{2}(s) \} / 2 \right] dB(s) , \end{aligned}$$

with $\phi_1 = \operatorname{corr}\{B\left(s\right), W_1\left(s\right)\}$ and $\phi_2 = \operatorname{corr}\{B\left(s\right), W_2\left(s\right)\}.$

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- Performance of the pseudo-marginal for RW proposal w.r.t σ , standard deviation of log $\hat{p}_{\theta}(y)$ at posterior mean $\overline{\theta}$.

Integrated Autocorrelation Time of Pseudo-Marginal MH



Figure: Average over the 9 parameter components of the log-integrated autocorrelation time of pseudo-marginal chain as a function of σ for T = 300.

(07/07/2016)

How precise should the log-likelihood estimator be?

• Aim: Minimize the computational time

$$CT_h^Q = IF_h^Q / \sigma^2$$

as $\sigma^2 \propto 1/N$ and computational efforts proportional to N, where

 IF_h^Q = Integrated Autocorrelation Time of PM average

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• Call the IACT the *inefficiency*

$$I\!F_{h}^{Q}=1+2\sum_{ au=1}^{\infty}\mathrm{corr}_{\overline{\pi},Q}\left\{ h\left(heta_{0}
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 , $h\left(heta_{ au}
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where Q is the pseudo-marginal kernel given for (heta,z)
eq (artheta,w) by

$$Q\left\{(\theta, z), (d\vartheta, dw)\right\} = q(\vartheta|\theta)g_{\vartheta}(w)\min\left\{1, \frac{\pi(\vartheta)}{\pi(\theta)}\exp(w-z)\right\}d\vartheta dw,$$

where

$$\begin{aligned} z &= \log\{\widehat{p}_{\theta}(y_{1:T})/p_{\theta}(y_{1:T})\}, \\ w &= \log\{\widehat{p}_{\theta}(y_{1:T})/p_{\theta}(y_{1:T})\}\}, \\ \end{aligned}$$

Computational time for the SV model



Figure: Computational time as a function of σ
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- Assumption 1 Asymptotic Normality: We have

$$\int \left| p\left(\theta \right| Y_{1:T} \right) - \phi(\theta; \widehat{\theta}^{T}, \Sigma/T) \right| d\theta \xrightarrow{P} 0,$$

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• Assumption 2 - CLT: For any θ in a neighbourhood of $\overline{\theta}$,

$$\log \frac{\widehat{p}_{\theta}(Y_{1:T})}{p_{\theta}(Y_{1:T})} \bigg| \mathcal{Y}^{T} \Rightarrow \mathcal{N} \left(-\sigma^{2} \left(\theta \right) / 2, \sigma^{2} \left(\theta \right) \right)$$

in probability and $\sigma^{2}(\cdot)$ continuous at $\overline{\theta}$.

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• Assumption 3 - Proposal: $\vartheta = \theta + \varepsilon / \sqrt{T}$ where $\varepsilon \sim v(\cdot)$ with $v(\varepsilon) = v(-\varepsilon)$.

 Assumption 1 holds if for example Bernstein-von Mises holds (in correctly specified/misspecified scenarios).

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- Assumption 1 holds if for example Bernstein-von Mises holds (in correctly specified/misspecified scenarios).
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- Assumption 2 has been shown to hold under regularity assumptions if N ∝ T (Berard et al, 2014, Deligiannidis et al, 2015).
- Assumption 3 can be easily enforced.

• Let $\{\vartheta_i^T, Z_i^T := \log \widehat{p}_{\vartheta_i^T}(Y_{1:T}) / p_{\vartheta_i^T}(Y_{1:T})\}_{i \ge 0}$ the stationary PM Markov chain of invariant density $p(\theta|Y_{1:T}) \exp(z) g_{\theta}^T(z)$.

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Weak convergence

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- **Proposition** (Schmon et al, 2016): The F.D.D. of the rescaled sequence $\{\widetilde{\vartheta}_i^T = \sqrt{T}(\vartheta_i^T - \widehat{\theta}_T), Z_i^T\}_{i \ge 0}$ converge weakly as $T \to \infty$ to those of a stationary Markov chain of invariant density $\phi\left(\widetilde{\theta}; 0, \Sigma\right) \phi\left(z; -\sigma^2\left(\overline{\theta}\right)/2, \sigma^2\left(\overline{\theta}\right)\right)$ and kernel given by $\widetilde{Q}\{(\widetilde{\theta}, z), (d\widetilde{\vartheta}, dw)\} = v(\widetilde{\vartheta} - \widetilde{\theta})\phi\left(w; -\sigma^2\left(\overline{\theta}\right)/2, \sigma^2\left(\overline{\theta}\right)\right)$ $\times \min\left\{1, \frac{\phi(\widetilde{\vartheta}; 0, \Sigma)}{\phi(\widetilde{\theta}; 0, \Sigma)}\exp\left(w - z\right)\right\} d\widetilde{\vartheta}dw$

$$\times \min \left\{ \begin{array}{l} 1, \frac{\gamma(z, y, z)}{\phi(\widetilde{\theta}; 0, \Sigma)} \right. \\ \\ \text{for } (\widetilde{\theta}, z) \neq (\widetilde{\vartheta}, w). \end{array} \right.$$

Weak convergence

• These results suggests that a simplified analysis of the PM chain can be performed by looking at

$$\widehat{Q}\{(\theta, z), (d\vartheta, dw)\} = q(\vartheta|\theta)\phi(w; -\sigma^2/2, \sigma^2)$$
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where $\sigma^2 = \sigma^2\left(\overline{ heta}
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• It would be more satisfactory to show that

$$|F_h^Q - |F_h^{\widehat{Q}}| \to 0$$

as $T \to \infty$. The analysis relies on (Andrieu & Vihola, 2015) and is much more involved.

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Empirical vs Assumed Distributions for SV model



Figure: Empirical distributions (dashed) vs assumed Gaussians (solid) of Z at $\overline{\theta}$ (left) and marginalized over samples from $\pi(\theta)$ (center) and $\int \pi(d\vartheta) q(\theta|\vartheta)$ (right) for T = 40, T = 300 and T = 2700.

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• Special cases:

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Special cases:

When q(θ|θ) = p(θ|y), σ_{opt} = 0.92 (Pitt et al., 2012).
 When π(θ) = Π^d_{i=1} f(θ_i) and q(θ|θ) is an isotropic Gaussian random walk then, as d → ∞, diffusion limit suggests σ_{opt} = 1.81 (Sherlock et al., 2015).

Sketch of the Analysis

• For general proposals and targets, direct minimization of $CT_{h}^{\hat{Q}}(\sigma) = IF_{h}^{\hat{Q}}(\sigma) / \sigma^{2}$ impossible so minimize an upper bound over it.

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- Theoretical study relies on $\overline{\pi}$ -invariant kernel Q^* given for $(\theta, z) \neq (\vartheta, w)$ by

$$q(\vartheta|\theta)\phi(w; -\sigma^2/2, \sigma^2)\min\left\{1, \frac{\pi(\vartheta)}{\pi(\theta)}\right\}\min\left\{1, \exp(w-z)\right\}d\vartheta dw,$$

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• Peskun's theorem (1973) guarantees that $IF_{h}^{\widehat{Q}}\left(\sigma\right) \leq IF_{h}^{Q^{*}}\left(\sigma\right)$ so that $CT_{h}^{\widehat{Q}}\left(\sigma\right) \leq CT_{h}^{Q^{*}}\left(\sigma\right)$.

Main Theoretical Result

• Proposition: If $IF_{h}^{Q^{*}}(\sigma) < \infty$ then $IF_{h}^{\widehat{Q}}(\sigma) \leq IF_{h}^{Q^{*}}(\sigma)$ and $IF_{h}^{Q^{*}}(\sigma) = 2\frac{\left\{1 + IF_{h}^{\mathsf{EX}}\right\}}{1 + IF_{h/\varrho_{\mathsf{EX}}}^{\widetilde{Q}^{\mathsf{EX}}}} \left\{\pi_{\mathsf{Z}}^{\sigma}(z)\left(1/\varrho_{\mathsf{Z}}^{\sigma}\right) - 1/\pi_{\mathsf{Z}}^{\sigma}(z)\left(\varrho_{\mathsf{Z}}^{\sigma}\right)\right\}$ $\times \sum_{n=0}^{\infty} \phi_{n}(h/\varrho_{\mathsf{EX}}, \widetilde{Q}^{\mathsf{EX}})\phi_{n}(1/\varrho_{\mathsf{Z}}, \widetilde{Q}_{\sigma}^{\mathsf{Z}})$ $+ \frac{1 + IF_{h}^{\mathsf{EX}}}{\pi_{\mathsf{Z}}^{\sigma}(\varrho_{\mathsf{Z}}^{\sigma})} - 1,$

where $\phi_n(\varphi, P)$ denotes the autocorrelation at lag *n* under a Markov kernel *P*.

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• $\widetilde{Q}^{\text{EX}}$ and $\widetilde{Q}^{\text{Z}}_{\sigma}$ correspond to the jump kernels associated to Q^{EX} and Q^{Z}_{σ} , $\varrho_{\text{EX}}(\theta)$ and $\varrho^{\sigma}_{\text{Z}}(z)$ are acceptance proba of Q^{EX} and Q^{Z}_{σ} .

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- This identity allows us to "decouple" the influence of the parameter and noise components on $IF_{h}^{Q^{*}}(\sigma)$.

Simpler Bounds on the Relative Inefficiency

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• If
$$IF_{h/\varrho_{\text{EX}}}^{Q^{\text{EX}}} \ge 1$$
, e.g. Q^{EX} is a positive kernel, then

$$\frac{IF_{h}^{\widehat{Q}}(\sigma)}{IF_{h}^{\text{EX}}} \le \frac{IF_{h}^{Q^{*}}(\sigma)}{IF_{h}^{\text{EX}}} \le \frac{1}{2}(1+1/IF_{h}^{\text{EX}})\pi_{Z}^{\sigma}(1/\varrho_{Z}^{\sigma}) - \frac{1}{IF_{h}^{\text{EX}}}$$

and the bound is tight as $IF_h^{\mathsf{EX}} \to 1$ or $\sigma \to 0$.

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and the bound is tight as $IF_{h}^{\text{EX}} \rightarrow 1$ or $\sigma \rightarrow 0$.
• As $IF_{J,h/\varrho_{\text{EX}}}^{\text{EX}} \rightarrow \infty$,

$$\frac{IF_{h}^{\mathsf{Q}}\left(\sigma\right)}{IF_{h}^{\mathsf{EX}}} \to \frac{1}{\pi_{\mathsf{Z}}^{\sigma}(\varrho_{\mathsf{Z}}^{\sigma})}.$$

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• Results used to minimize w.r.t σ upper bounds on $CT_{h}^{\hat{Q}}(\sigma) = IF_{h}^{\hat{Q}}(\sigma) / \sigma^{2}.$

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Bounds on Relative Computational Time



Left: upper bound on $CT_h^{Q^*}(\sigma) / IF_h^{\mathsf{EX}}$ as a function of σ for $IF_h^{\mathsf{EX}} = 1$ (square), 4 (crosses), 20 (circles), 80 (triangles). Right: upper bounds on $CT_h^{Q^*}(\sigma) / IF_h^{\mathsf{EX}}$ as a function of σ for $IF_{J,h//\varrho_{\mathsf{EX}}}^{\mathsf{EX}} = 1$ for $IF_{J,h//\varrho_{\mathsf{EX}}}^{\mathsf{EX}} = 1, 4, 20, 80$ and lower bound (solid line).

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- For good proposals, select $\sigma\approx 1.0$ whereas for poor proposals, select $\sigma\approx 1.7.$
- When you have no clue about the proposal efficiency,
- If $\sigma_{\rm opt} = 1.0$ and you pick $\sigma = 1.7$, computing time increases by $\approx 150\%$.
- If $\sigma_{\rm opt} = 1.7$ and you pick $\sigma = 1.0$, computing time increases by $\approx 50\%$.
- If $\sigma_{\rm opt} = 1.0$ or $\sigma_{\rm opt} = 1.7$ and you pick $\sigma = 1.2 1.3$, computing time increases by $\approx 15\%$.

• Consider

$$\begin{split} X_t &= \quad \mu(1-\phi) + \phi X_t + V_t, \quad V_t \overset{\text{i.i.d.}}{\sim} \mathcal{N}\left(0, \sigma_{\eta}^2\right), \\ Y_t &= \quad X_t + W_t, \quad W_t \overset{\text{i.i.d.}}{\sim} \mathcal{N}\left(0, \sigma_{\varepsilon}^2\right), \\ \end{split}$$
 where $\theta &= \left(\phi, \mu, \sigma_{\eta}^2\right). \end{split}$

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- N is selected so as to obtain $\sigma(\overline{\theta}) \approx \text{constant}$ where $\overline{\theta}$ posterior mean.

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Relative Inefficiency and Computing Time



Figure: From left to right: RCT_h^Q vs N, RCT_h^Q vs $\sigma(\overline{\theta})$, RIF_h^Q against N and RIF_h^Q against $\sigma(\overline{\theta})$ for various values of ρ and different parameters.
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- Optimal σ depends on efficiency of the ideal MH algorithm but $\sigma\approx 1.2$ is a sweet spot.
- Pseudo-marginal MH scales in O (T²) as we require N ∝ T, while simulated likelihood scales in O (T^{3/2}), i.e. N ∝ √T.
- However, pseudo-marginal MH much more generally applicable than simulated likelihood.

The Correlated Pseudo-Marginal Algorithm

Reparameterize the likelihood estimator p
θ (y{1:T}) as a function of normal variates U ~ N (0, I)

$$\widehat{p}_{\theta}\left(y_{1:T}\right) = \widehat{p}_{\theta}\left(y_{1:T}; U\right)$$

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• In practice, ρ will be select close to 1.

Correlated Pseudo-Marginal Metropolis-Hastings algorithm

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<u>At iteration i</u>

• Sample $\vartheta \sim q\left(\cdot \mid \vartheta_{i-1}\right)$ and $V = \rho U_{i-1} + \sqrt{1 - \rho^2} \varepsilon$, $\varepsilon \sim \mathcal{N}\left(0, I\right)$.

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- With probability

$$\min\{1, \frac{\widehat{p}_{\vartheta}(y_{1:T}; V)}{\widehat{p}_{\vartheta_{i-1}}(y_{1:T}; U_{i-1})} \frac{p(\vartheta)}{p(\vartheta_{i-1})} \frac{q(\vartheta_{i-1}|\vartheta)}{q(\vartheta|\vartheta_{i-1})}\}$$

set $\vartheta_i = \vartheta$, $U_i = V$, otherwise set $\vartheta_i = \vartheta_{i-1}$, $U_i = U_{i-1}$.

Proposition. Let $N = N(T) \rightarrow \infty$ as $T \rightarrow \infty$ with N = o(T). When $U \sim \overline{\pi}(\cdot|\theta)$ and $V = \rho_T U + \sqrt{1 - \rho_T^2} \varepsilon$ with $\rho_T = \exp\left(-\psi \frac{N}{T}\right)$ then as $T \rightarrow \infty$

$$\log\left\{\frac{\widehat{p}_{\theta+\xi/\sqrt{T}}(y_{1:T};V)}{\widehat{p}_{\theta}(y_{1:T};U)}/\frac{p_{\theta+\xi/\sqrt{T}}(y_{1:T})}{p_{\theta}(y_{1:T})}\right\} \middle| \mathcal{Y}^{T}, \mathcal{U}^{T} \Rightarrow \mathcal{N}(-\frac{\kappa^{2}(\theta)}{2}, \kappa^{2}(\theta)).$$

 This CLT is conditional on the observation sequence and the current auxiliary variables.

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- The asymptotic variance is O(1) even for $N \sim \log(T)$.

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• Assumption 1 - Asymptotic Normality: We have

$$\int \left| p\left(\theta \right| Y_{1:T} \right) - \phi(\theta; \widehat{\theta}^{T}, \Sigma/T) \right| d\theta \xrightarrow{P} 0,$$

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- Assumption 2 Proposal: $\vartheta = \theta + \xi / \sqrt{T}$ where $\varepsilon \sim v(\cdot)$ with $v(\xi) = v(-\xi)$.
- Assumption 3 For any θ in a neighbourhood of $\overline{\theta}$, the conditional CLT holds and $\kappa^2(\cdot)$ is continuous at $\overline{\theta}$.

Weak convergence

• Let $\{\vartheta_i^T\}_{i\geq 0}$ the stationary non-Markovian sequence of the correlated PM of invariant density $p(\theta | Y_{1:T})$.

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- Let $\{\vartheta_i^T\}_{i\geq 0}$ the stationary non-Markovian sequence of the correlated PM of invariant density $p(\theta|Y_{1:T})$.
- Proposition (Deligiannidis et al., 2016): The F.D.D. of the rescaled sequence {θ̃_i^T = √T(θ_i^T θ̂_T)}_{i≥0} converge weakly as T → ∞ to those of a stationary Markov chain of invariant density φ(θ̃; 0, Σ) and kernel given for θ̃ ≠ θ̃ by

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• These results suggests that a simplified analysis of the CPM chain can be performed by looking at

$$\widehat{Q}(heta, \mathrm{d}artheta) = q\left(artheta| heta
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$$\mathbb{C}\mathrm{ov}\left(\theta_{0},\theta_{\tau}\right)\approx\underbrace{\mathbb{E}\left(\mathbb{C}\left(\theta_{0},\theta_{\tau}|U_{0},U_{\tau}\right)\right)}_{\mathsf{fast}}+\underbrace{\mathbb{C}\left(\mathbb{E}\left(\theta_{0}|U_{0}\right),\mathbb{E}\left(\theta_{\tau}|U_{\tau}\right)\right)}_{\mathsf{slow}}$$

where $\mathbb{E}(\theta_0|U_0) \approx \widehat{\theta}^T + \Sigma / T \nabla_{\theta} \log \widehat{p}_{\theta}(y_{1:T}; U) / p_{\theta}(y_{1:T})|_{\widehat{\theta}^T}$ and $IF_h^Q \to \infty$ if $N/\sqrt{T} \to 0$.

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 ight) = heta$

$$\mathbb{C}\mathrm{ov}\left(\theta_{0},\theta_{\tau}\right)\approx\underbrace{\mathbb{E}\left(\mathbb{C}\left(\theta_{0},\theta_{\tau}\mid U_{0},U_{\tau}\right)\right)}_{\mathrm{fast}}+\underbrace{\mathbb{C}\left(\mathbb{E}\left(\theta_{0}\mid U_{0}\right),\mathbb{E}\left(\theta_{\tau}\mid U_{\tau}\right)\right)}_{\mathrm{slow}}$$

where $\mathbb{E}(\theta_0 | U_0) \approx \widehat{\theta}^T + \Sigma / T \nabla_{\theta} \log \widehat{p}_{\theta}(y_{1:T}; U) / p_{\theta}(y_{1:T})|_{\widehat{\theta}^T}$ and $IF_h^Q \to \infty$ if $N/\sqrt{T} \to 0$.

• To ensure IF_h^Q , we need at least $N \propto \sqrt{T}$ and we conjecture it is sufficient.

$$X_t \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(\theta, 1), \quad Y_t | X_t \sim \mathcal{N}(X_t, \sigma^2).$$

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- Integrated Autocorrelation Time is referred to as the Inefficiency IF.

Example: Gaussian Latent Variable Model

MH (<i>T</i> = 8192)		$IF(\theta)$	
		15.6	
PM ($ ho=$ 0.0)			
N		$RIF(\theta)$	$RCT(\theta)$
5000		2.2	11210
CPM ($ ho=$ 0.9963)			
Ν	κ	$RIF(\theta)$	$RCT(\theta)$
9	3.1	14.0	126.2
12	2.7	8.3	99.7
20	2.2	4.7	93.3
25	2.0	2.8	69.3
35	1.7	1.7	61.1
56	1.3	1.6	87.0
80	1.1	1.1	89.0
120	0.9	0.9	113.5

Here $RIF = IF/IF_{MH}$ and $RCT = N \times RIF$.

(07/07/2016)

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- Novel pseudo-marginal scheme using Conditional Sequential Monte Carlo (Andrieu, A.D., Yildirim, 2016) appears to suggest O(T) is feasible.

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	Novel c-SMC PM		Standard PM		
	σ_v^2	σ_w^2	σ_v^2	σ_w^2	
T = 1000	17.7	23.5	71.2	59.2	
T = 2000	17.5	23.7	759.0	757.9	
T = 5000	17.6	23.7	5808.6	5663.5	
T = 10000	17.6	23.6	7368.1	7176.9	

Estimated IACT on a nonlinear state-space model for N = 200 for novel c-SMC PM algorithm and N = 2000 for standard PM algorithm

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